

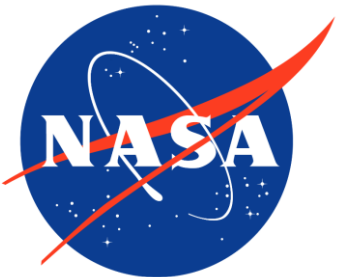
# Source and Sink Attributions From Satellites Using Deep Learning Models

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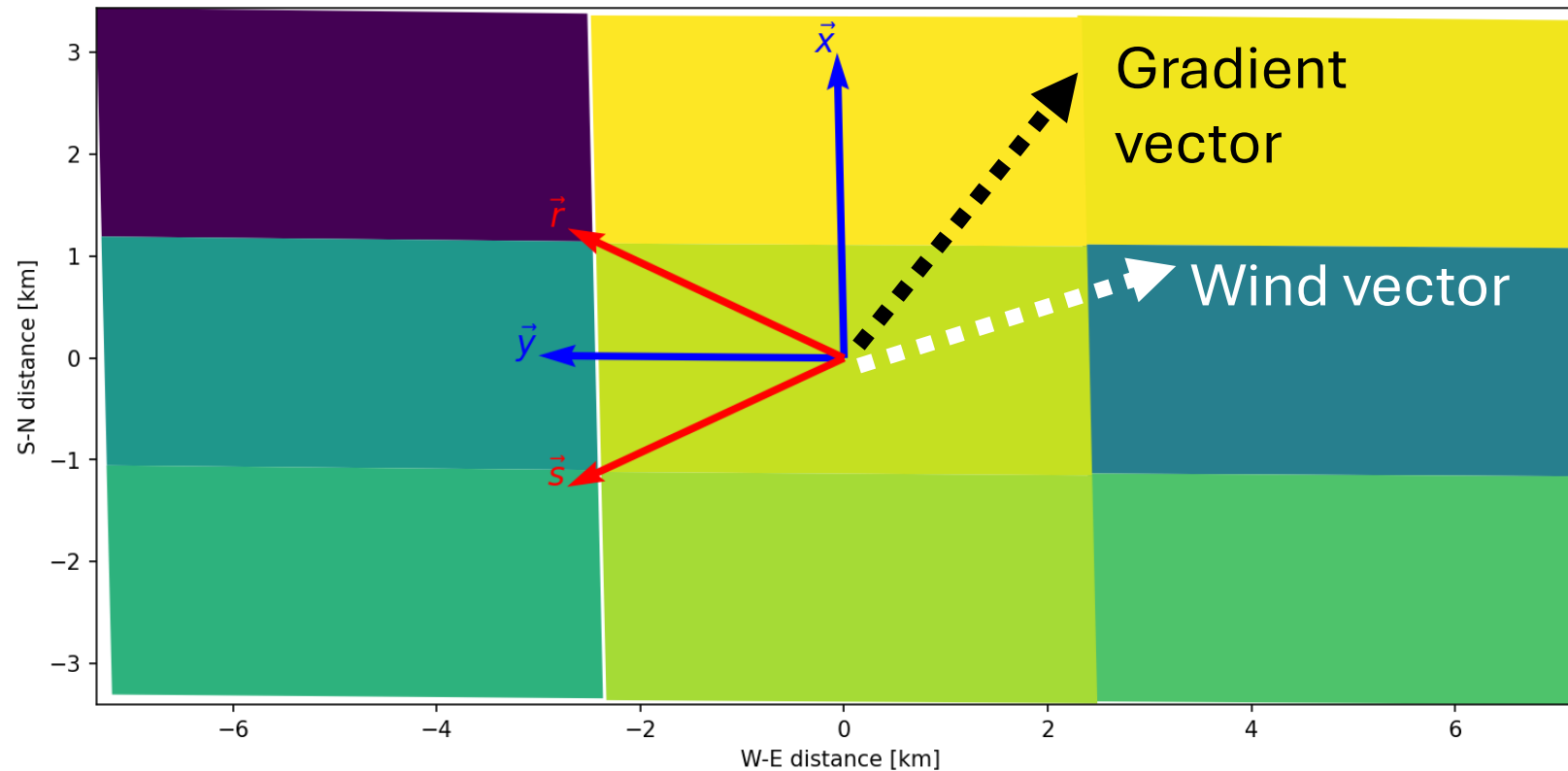
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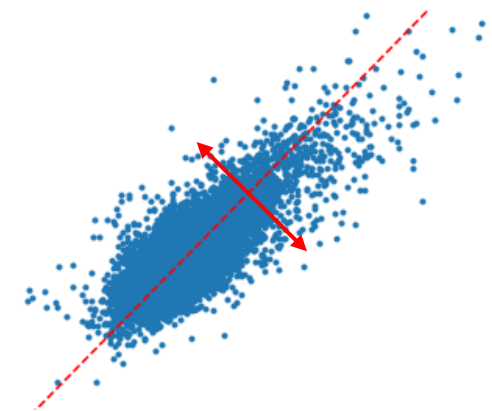
# Directional derivative (DD) of satellite columns ( $\Omega$ ) reflects flux

- “xy” realization:  $\vec{u} \cdot (\nabla\Omega) = u_x \frac{\partial\Omega}{\partial x} + u_y \frac{\partial\Omega}{\partial y}$  DD = gradient dot wind



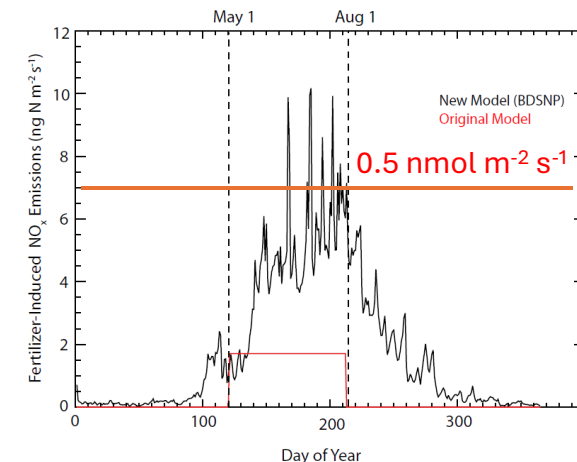
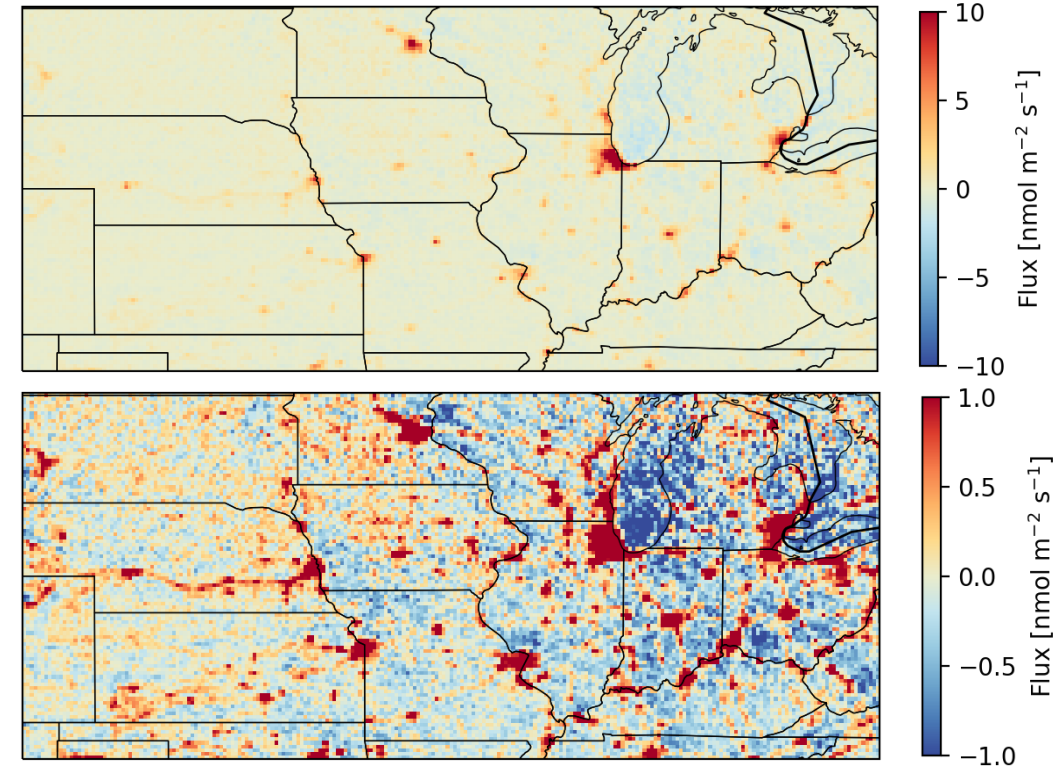
- “rs” realization:  $\vec{u} \cdot (\nabla\Omega) = u_r \frac{\partial\Omega}{\partial r} + u_s \frac{\partial\Omega}{\partial s}$

- xy and rs are random (noisy) realizations of the same signal:



# Where is soil NO<sub>x</sub> on a multiyear DD (net flux) map?

- Midwest corn receives intensive nitrogen fertilization, yet soil NO<sub>x</sub> does not show up as the second largest source
- Signal vs. noise vs. interference:
  - Aggregated monthly, the noise floor is  $\sim 1\text{-}2$   $\text{nmol m}^{-2} \text{s}^{-1}$
  - Peak fertilizer-induced NO<sub>x</sub> < half of noise
  - Over a satellite-resolvable grid ( $\sim 10$  km), corn accounts for 20%-40% at heart of corn belt
    - Diluted most by soybeans (little N fertilization) -> signal  $\sim 10\%$  of noise at 1M
  - Fossil fuel interferences at  $10\text{s}$   $\text{nmol m}^{-2} \text{s}^{-1}$
  - Chemical loss at  $-(0.5\text{-}1)$   $\text{nmol m}^{-2} \text{s}^{-1}$ 
    - Soil NO<sub>x</sub> signal typically “under the water”



Hudman et al. 2012, ACP

# Theory relating DD to sources and sink

$$\bullet E = \underbrace{\vec{u} \cdot (\nabla \Omega)}_{\text{DD of } \Omega} + \underbrace{k\Omega}_{\text{Sink}} + \underbrace{X\Omega\vec{u}_0 \cdot (\nabla z_0)}_{\text{Topography}}; \quad k: \text{ reactivity}; X: \text{ inverse scale height}$$

Source

- Decomposing emissions sources as  $E = \sum E_i F_i$ 
  - Example: two same-acreage land types ( $F_1 = F_2 = 50\%$ ) with emissions  $E_1 = 9.5 \text{ nmol m}^{-2} \text{ s}^{-1}$  and  $E_2 = 0.5 \text{ nmol m}^{-2} \text{ s}^{-1}$  give  $E = 5 \text{ nmol m}^{-2} \text{ s}^{-1}$
- Rearrange:
  - $\vec{u} \cdot (\nabla \Omega) = k(-\Omega) + X(-\Omega\vec{u}_0 \cdot (\nabla z_0)) + E_1 F_1 + E_2 F_2 + \dots$
- Like a linear regression model (**target** = sum(**coefficient** x **predictor**)), but
  - Coefficients are functions of space and time (lat, lon, linear trend, seasonality)
  - Coefficients *must be non-negative*
  - Coefficients should be spatially smooth, and not significantly correlated
  - Coefficients learned as a feature-wise-modulated U-Net (~9e6 parameters)
- Wrapped by a learnable super-Gaussian point-spread function

# Spatial model prediction

- Trained on 3M S5PNO2; Inference monthly
- Averaging models with 5-fold cross validation
- Note missing point sources not yet modeled

